

UNIVERSITÀ DI PISA

UNIVERSITÀ DI PISA CONSIGLIO NAZIONALE DELLE RICERCHE UNIVERSIDADE FEDERAL DE SANTA CATARINA

Mauriana Pesaresi Seminar Series 2021/2022

Movelet-based Classification of Multiple Aspect Trajectories

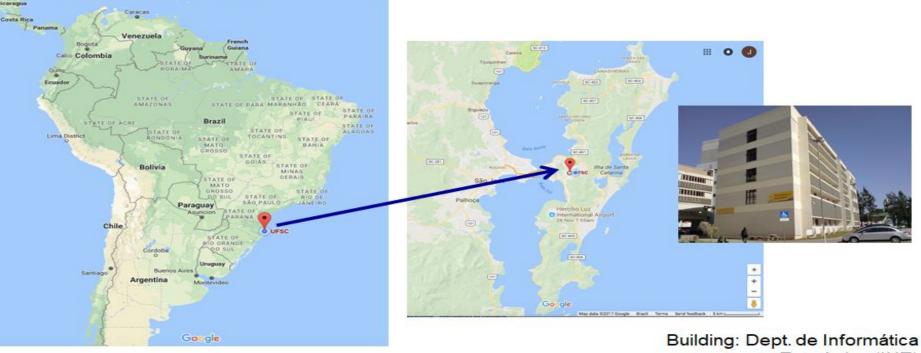
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Spatial Location

Universidade Federal de Santa Catarina Campus Florianópolis



UFSC: Universidade Federal de Santa Catarina

UFSC main campus



Founded in 1960, UFSC offers all Programs for free (no tuition)

- 107 Undergraduate Programs
- 65 Master Programs
- 56 PhD Programs
- 30.000 undergraduate students

3

15.000 graduate students

5th Best University in Brazil 12th Best in Latin America



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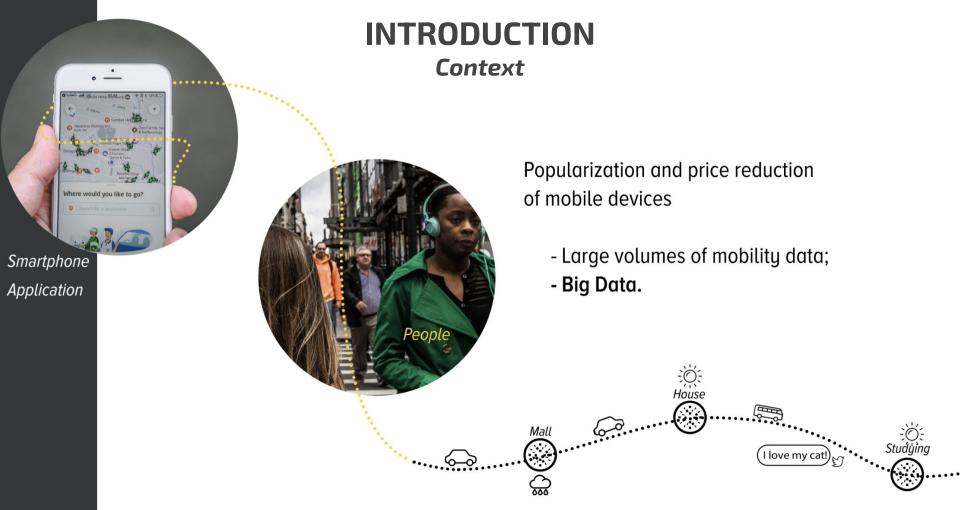
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INTRODUCTION *Trajectory Classification*

- Trajectory data mining is important for discovering interesting knowledge and behavior about different objects as people, animals, vehicles, weather condition;
- An important data mining technique is classification:

Trajectory classification is the task of discovering the class label of a moving object based on its trajectories (Lee et al.2008).

INTRODUCTION Motivation

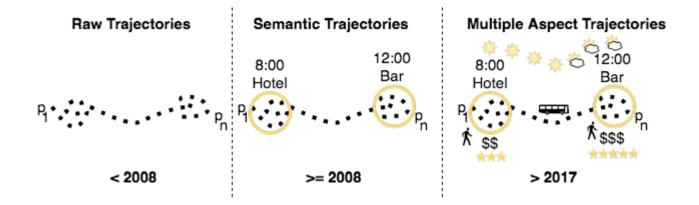


Applications of Trajectory Classification

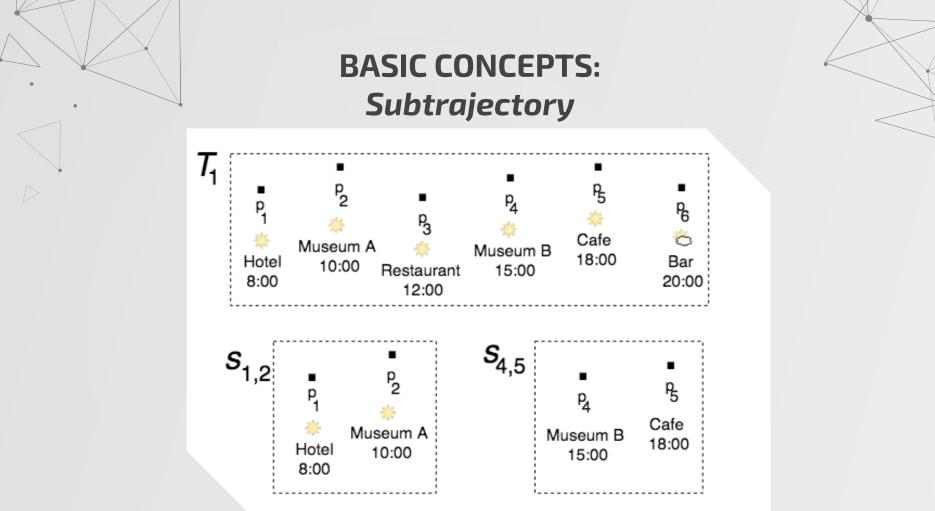
- a. Transportation mean classification;
- b. The strength level of a hurricane / Natural disaster prediction;
- c. The type of a vessel;
- d. Animal categories
- e. The moving object, owner of the trajectory.



BASIC CONCEPTS: Trajectory

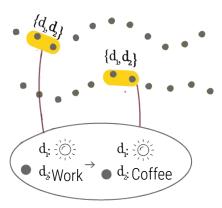


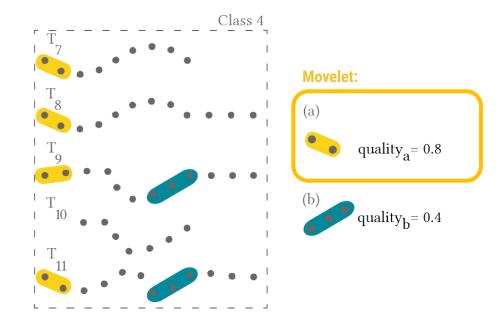
- → A **Multiple Aspect Trajectory** T_i is a sequence of *m* elements $T_i = \langle e_1, e_2, ..., e_m \rangle$, where each element is characterized by a set of *l* dimensions D={ d₁, d₂, ..., d₁ }, also called aspects.
- → Multiple and heterogeneous dimensions. [Ferrero et al., 2016; Mello et al., 2019]



Basic Concepts: What is a movelet?

Inspired by time series shapelet [Ye, L.; Keogh, E., 2011] a movelet is a subtrajectory that used by a classifier, better discriminate a class:



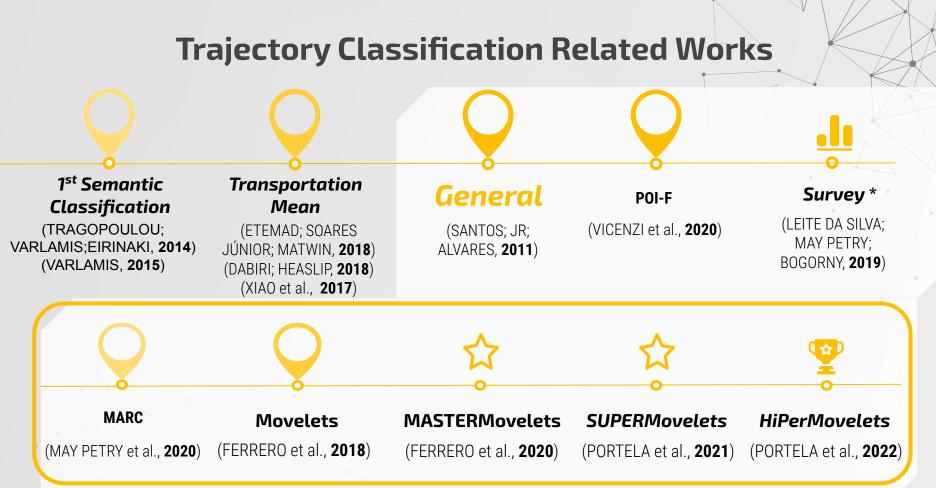


PROBLEM DEFINITION

• The problem of trajectory classification relies on finding the best *trajectory* or *subtrajectory* features to use as input to a classifier;

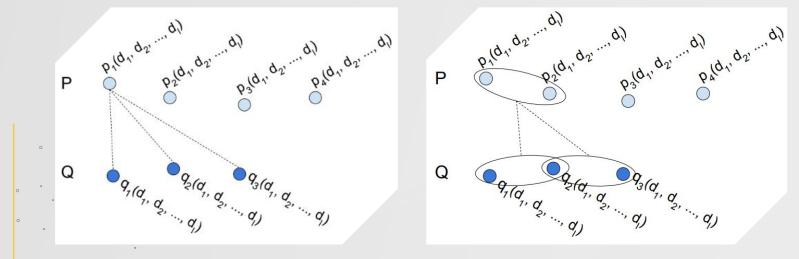
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- Related works do not propose new classifiers (RF, NN, DT)
- So far, Movelets has been one of the best approaches:
 - highest accuracy
 - general problems
 - Interpretable patterns;

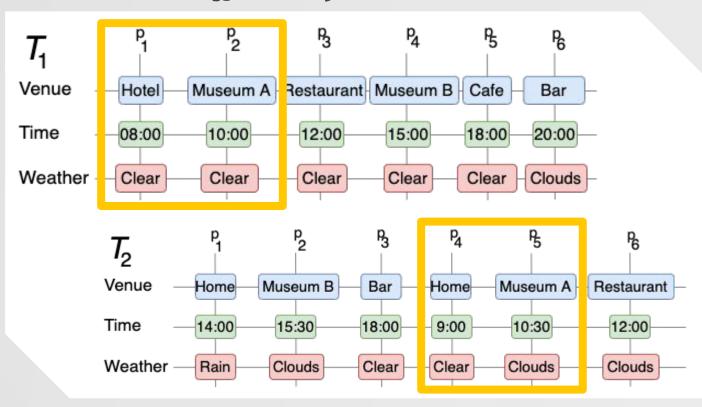


MOVELETS EXTRACTION MASTERMovelets

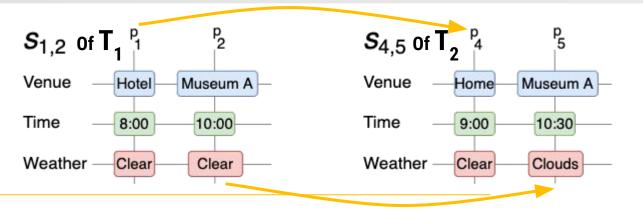
- Parameter free;
- Analyze every possible subtrajectory and computes the distance of all subtrajectories of the same size in the dataset.



RESEARCH PROBLEM: *How to efficiently extract movelets?*



Basic Concepts: Subtrajectory Distances



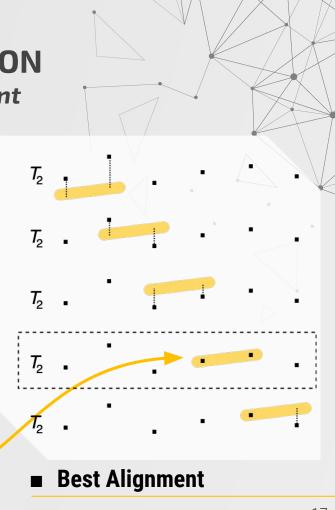
Element Distances			Sul	otrajectory Distances (V)
1	0			0.5
(Hotel <> Home)	(Museum A <> Museum A)	v_1		((1+0) / 2)
60	30	\rightarrow		45
(8:00 <> 9:00)	(10:00 <> 10:30)		v_2	((60 + 30) / 2)
0	0			0.5
(Clear <> Clear)	(Clear <> Clouds)		v_3	((0+1)/2)

MOVELETS EXTRACTION

Ranking and Best Alignment

Ranking distances

Distance	e Start	Starting Position							
	p_1	p_2	p_3	p_4	p_5				
Venue	1	1	1	0.5	1				
Time	345	465	330	45	135	5			
Weather	1	0.5	0	0.5	1				
Vector	\mathbf{V}_1	\mathbf{V}_2	\mathbf{V}_3	\mathbf{V}_4	\mathbf{V}_5				
_	Ranki	ngs	Starting Position						
		_	p_1	p_2	p_3	p_4	p_5		
	Venue		2	2	2	1	2		
	Time	4	5	3	1	2			
	Weathe	3	2	1	2	3			
_	Avg. R	4.5	4.5	3	2	3.5			

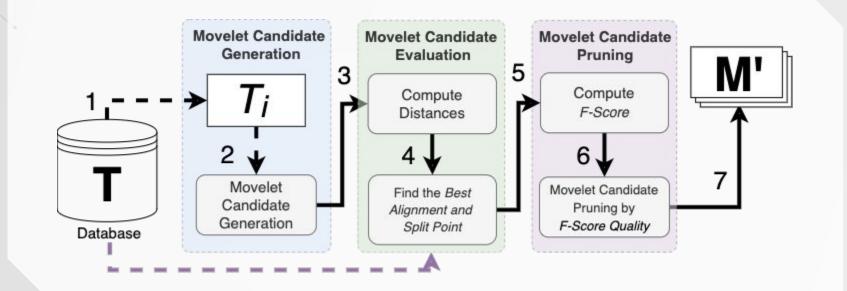


MOVELETS EXTRACTION Finding the Split Point T_5 Venue Covers T5 Split point for Venue {T₁, T₂, T₃} **F-score** POI = 1.0 T₂ T3 0.5 T₂ T3 0.5 Split point Covers {T₁} for Time **T**4 Time 0 T4 Time 0 -20 40 60 80 100 120 140 20 60 80 40 100 120 140 0

0



MASTERMovelets



(Ferrero et. al, 2020)



MASTERMovelets Complexity

- \blacksquare **n** \rightarrow the number of trajectories;
- \blacksquare **m** \rightarrow the length of the longest trajectory, and;
- \blacksquare \blacksquare \rightarrow the number of dimensions in the dataset

Memory: it stores at most n × m candidates for all trajectories.

 $O(n \times m^2 \times I) \rightarrow Matrix of Distances *$

Running Time: the overall time complexity is $O(x^2 + x^2)$

 $O(n^3 \times m^3 \log m \times 2^l)$

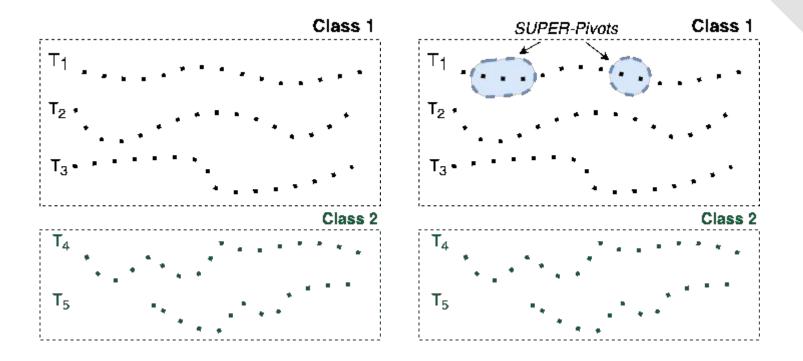
■ Limitations:

 \circ $\,$ Unfeasible for Big Data and high dimensional datasets.

MASTERMovelets

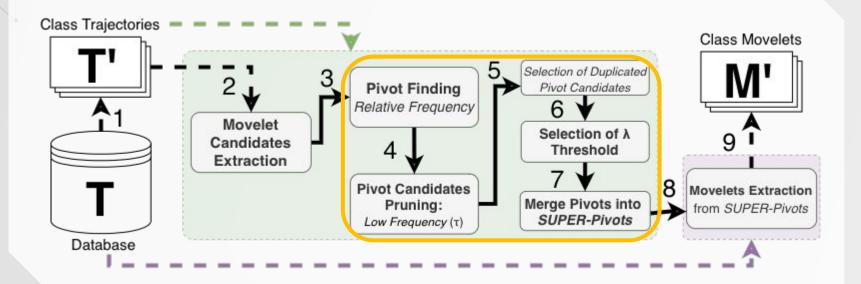
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SUPERMovelets





SUPERMovelets



Fast Movelet Extraction and Dimensionality Reduction for Robust Multiple Aspect Trajectory Classification. In Brazilian Conference on Intelligent Systems (BRACIS), 2021.



EXPERIMENTAL RESULTS Highlights

SUPERMovelets movelet extraction:

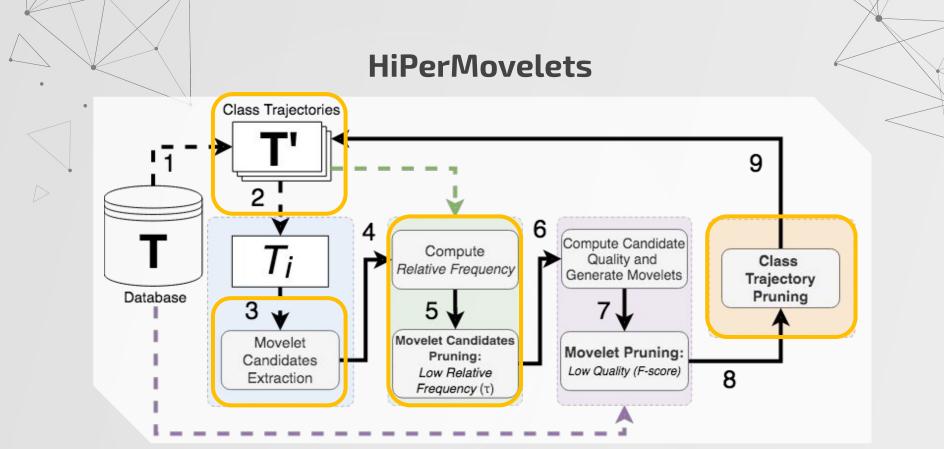
• Movelet extraction at least 50% faster than MASTERMovelets;

SUPERMovelets accuracy:

- Same accuracy as MASTERMovelets (less than 1% difference);
- Generates significantly less movelets (65-93% reduction);
- Faster to build classification models.

Limitations:

• Unfeasible for Big Data and high dimensional datasets*



HiPerMovelets: high-performance movelet extraction for trajectory classification. International Journal of Geographical Information Science, 2022. DOI: 10.1080/13658816.2021.2018593



EXPERIMENTAL RESULTS Highlights

■ HiPerMovelets in Multiple Aspect Trajectories Datasets (check-ins):

- Run time is up to 10x faster than MASTERMovelets;
- Higher or same accuracy than MASTERMovelets;;
- Generates less movelet candidates and movelets.

■ Limitations:

• Unfeasible for Big Data and high dimensional datasets.

Open Issues:

- For which domains Movelets are best suited? (Multiple Aspect Trajectories and Multivariate Time Series)
 Which are the best strategies to extract movelets?
 - (Optimizing search for Best alignment and Split points)
- How to improve classification methods? (Employing movelets in Multivariate Time Series Classification, and vice-versa)

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THANKS

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> Mauriana Pesaresi Seminar Series 2021/2022

Methods for Movelets Extraction Multidimensional Sequence Classification

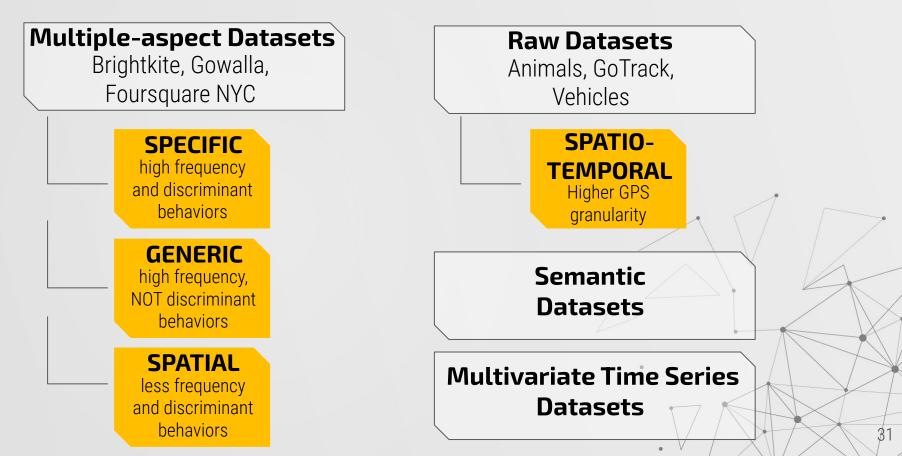
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DATASETS



Time Series Optimization

EARLY ABANDONING

(YE; KEOGH, 2011) (MUEEN; KEOGH; YOUNG, 2011)

SAX

(RAKTHANMANON; KEOGH, 2013)

SAMPLING THE DATASET (JI et[°]al., 2019).

ANALYSIS OF VARIANCE A(NOVA) (ZUO; ZEITOUNI; TAHER, 2018)

LOCAL FISHER DISCRIMINANT ANALYSIS (LFDA)

(ZHANG et al., 2018)

PROPOSED OPTIMIZATIONS

A) Pruning based on repetition

(prunes candidates that doesn't repeat in the trajectory)

B) Pruning based on frequency

(prunes less frequent candidates)

C) Random selection * for baseline (randomly select candidates to evaluate as movelets)

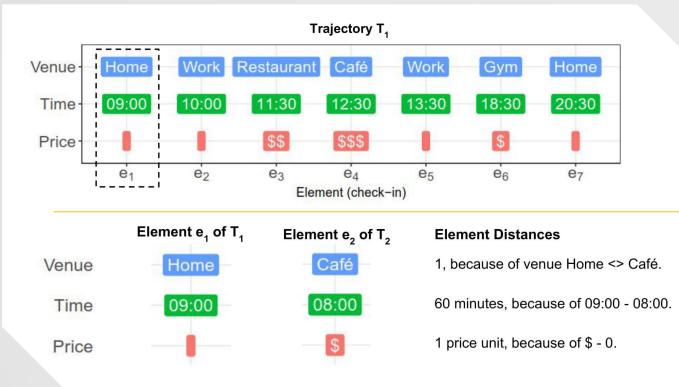
OBJECTIVE

Propose new methods to optimize the *movelets discovery for trajectory classification.*

- Propose techniques for trajectory classification based on reducing the search space, dimensionality and number of comparisons;
 - An algorithm to reduce the search space for extracting movelets;
 - An algorithm to reduce the number of dimensions for extracting movelets;
 - An algorithm that uses a multidimensional index to reduce the number of comparisons for extracting movelets;
- Experiments for validating the proposed method and MASTERMovelets (scalability, comparisons of accuracy, processing time, classification times and number of movelets).



Basic Concepts: Element Distances

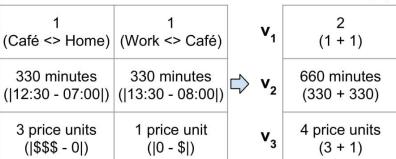


Basic Concepts: Subtrajectory Distances

Subtrajectory s₄ of T₁ Subtrajectory s₁ of T₂



Element Distances

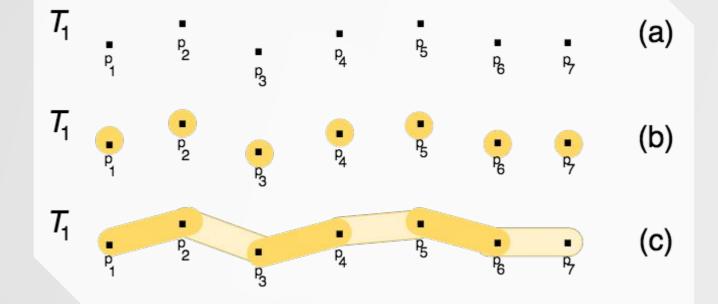


Subtrajectory

Distance (V)

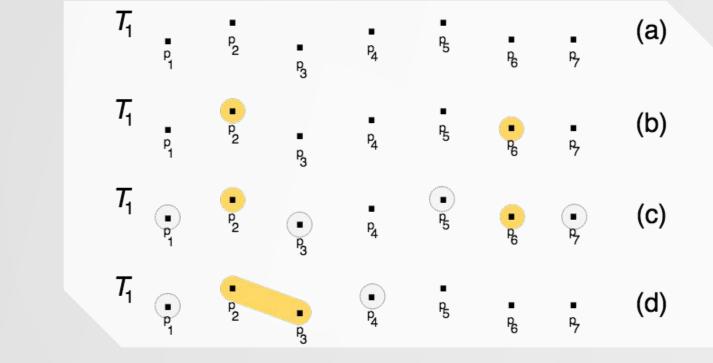


HiPerMovelets

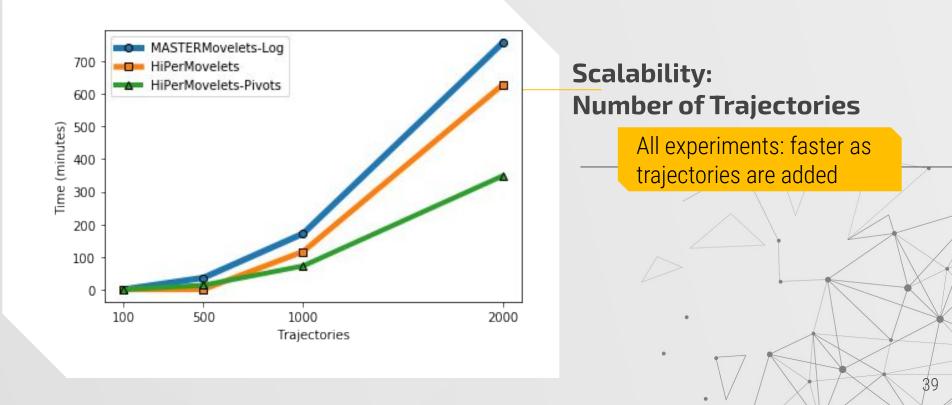




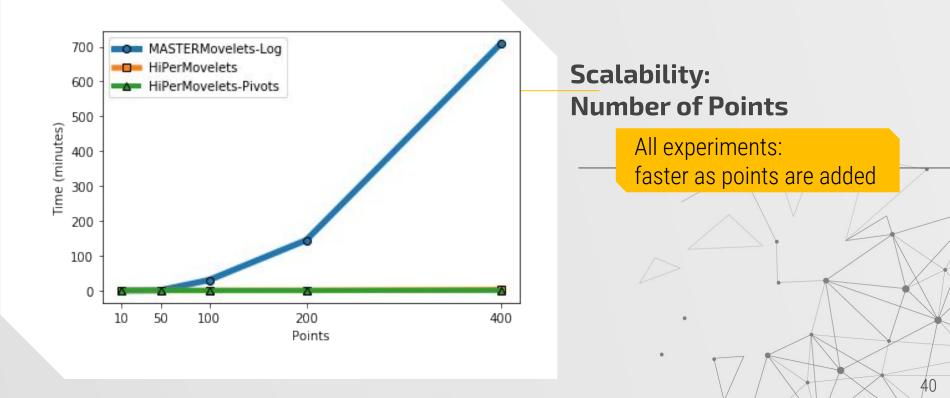
HiPerMovelets *Pivots*



EXPERIMENTAL RESULTS



EXPERIMENTAL RESULTS



EXPERIMENTAL RESULTS

